

2025 Fall Conference at Ashore Resort & Beach Club Ocean City, Maryland Surveying Technology

September 19, 2025

Paul S. Ewell, Professional Land Surveyor Nick Alexander, Professional Land Surveyor



Paul S. Ewell

- § Professional Land Surveyor MD & PA
- § AA Degree in Land Surveying Technology
- § Past President of Maryland Society of Surveyors
- § 2024 MSS Surveyor of the Year
- § MSS Workforce Development Committee Chairman







§ Surveying for 39 years

Nick Alexander

- § Maryland Professional Land Surveyor
- § MSS Young Surveyors Chapter Chairman
- § 2024 Inaugural MSS Surveying Technician of the Year
- § FAA Part 107 UAS Licensed Drone Pilot





ABSTRACT

SURVEYING TECHNOLOGY

- § Geodetic Datums Brief history and what's coming
- § GPS current applications
- § Bathymetric Surveying
- § Terrestrial Scanning and Mobile Mapping
- § Drone UAS Surveying
- § Other tech

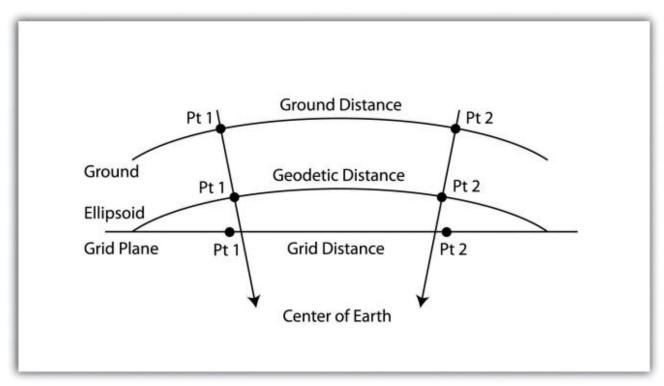
§ One hour session for 1.0 PDH

GEODETIC DATUM EVOLUTION (Horizontal)

Grid versus Ground (what is state plane and why have it)

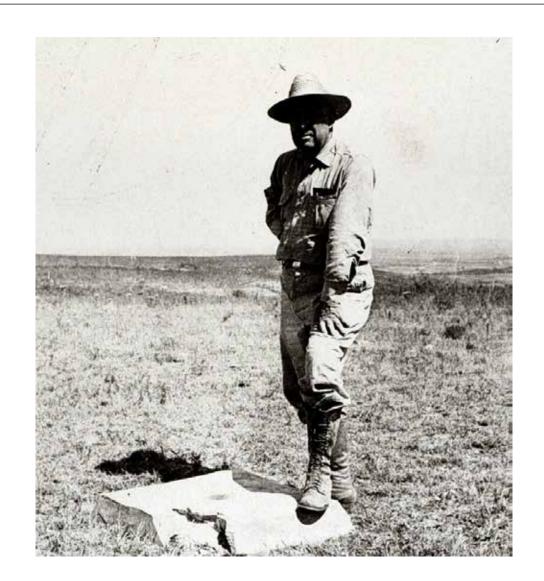
Exists to provide a more accurate and practical method for surveying and mapping within specific regions of the United States

- Minimize Distortion
- Better local accuracy
- Simpler Calculations



GEODETIC DATUM EVOLUTION (Horizontal)

- § NAD 27 (North American Datum of 1927)
 - NAD 27 was based on network of triangulation stations and a Clarke Ellipsoid of 1866.
 - Established from a single reference point at Meades Ranch in Kansas



GEODETIC DATUM EVOLUTION (Horizontal)

- § NAD 83 (North American Datum of 1983)
 - NAD 83 replaced NAD 27 and offered a more accurate representation of the earths shape.
 - Was released in 1986 with state by state adjustments in the 1990's. Utilized both classical triangulation and newer GPS observations.
 - First iteration was NAD 83 (1991) All classical triangulation adjusted to fit HARN. High Accuracy Reference Network established by state GPS surveys.
 - CORS (Continuously Operating Reference Stations)
 - Next iteration was NAD 83 (2007), All passive control adjusted to fit CORS network positions (67,000+ stations)
 - Current iteration is NAD 83 (2011), All passive control adjusted to fit CORS network positions (80,000+ stations)

GEODETIC DATUM EVOLUTION (Horizontal)

- § Where we're going
 - NATRF2022 (North American Terrestrial Reference Frame)
 - Provides greater accuracies while incorporating modern technologies.
 - More aligned with true "Earth Center".
 - Will rely primarily on GNSS and updated Geoid models from GRAV-D project.
 - Plat Tectonics factor. (new epochs)
 - More defined with positional velocities.

GEODETIC DATUM EVOLUTION (Vertical)

- § NGVD 29 (National Geodetic Vertical Datum of 1929)
 - Also known as Sea Level Datum of 1929.
 - Based on mean sea level observations at 26 tidal stations.
 - Later found to have inaccuracies due to variations in local mean sea levels
- § NAVD 88 (North America Vertical Datum of 1988)
 - A more comprehensive adjustment using leveling data, gravity factors and GPS measurements.
 - Aimed to provide a more accurate and consistent vertical refence system.
 - Accounts for variations in gravity and earth distortions.
 - Does not easily account for local vertical velocities.

GEODETIC DATUM EVOLUTION (Vertical)

- § Where we're going
 - NAPGD 2022 (North American-Pacific Geopotential Datum of 2022)
 - Realized by new GEOID 2022
 - GRAV-D Project (Gravity for the Redefinition of the American Vertical Datum)
 - Airbourne Gravity snapshot with absolute gravity tracking.
 - Geoid will be tracked over time to keep datum up to date.

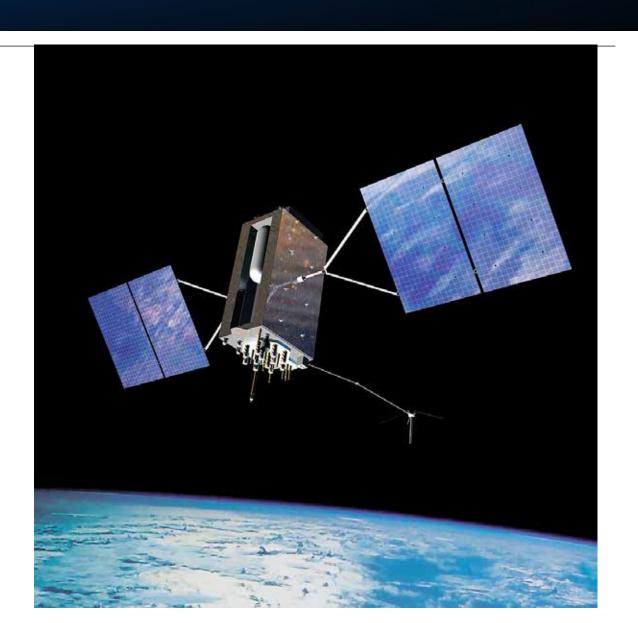
PSA – You CANNOT improve the accuracy of coordinates and elevations by performing datum conversions!

GNSS APPLICATIONS

- § GPS developed by US Military in 1995 using 31 satellites.
- § GLONASS developed by Russia in 1995 using 24 satellites.
- § Galileo developed by European Union launched in 2016 and has 27 usable satellites.
- § BeiDOU developed by China first launched in 2000 and has 35 usable satellites.
- § Current Survey equipment is GNSS meaning it uses all the above signals (more signals = better results)

GPS SATELLITES

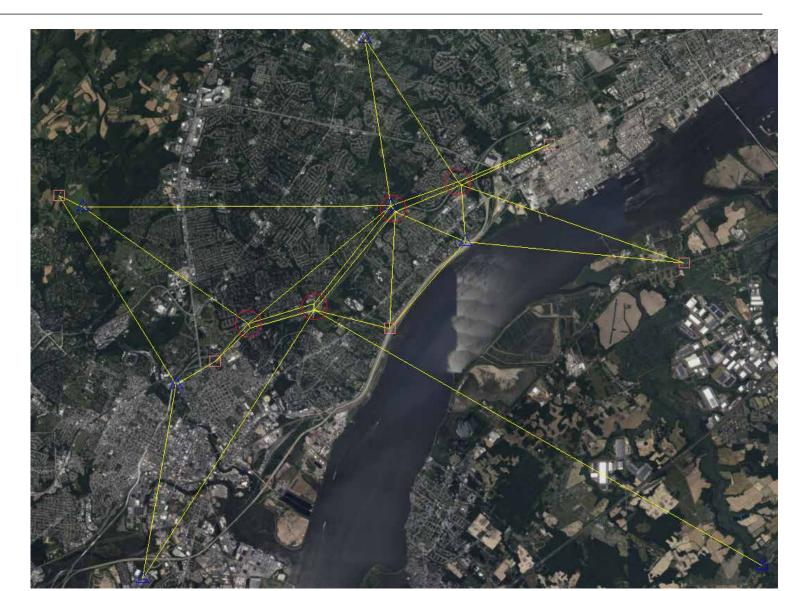
- § 1978 Block I satellites started.
- § 1989 Block II satellites started.
- § 1995 Block I fully operational.
- § 2000 Selective availability turned off.
- § 2018 Block III satellites started.
- § 2027-2028 Block III fully operational (maybe)
- § 2028-2031 0.3 to 1.6 feet real time accuracy



GNSS APPLICATION

§ Static Networks

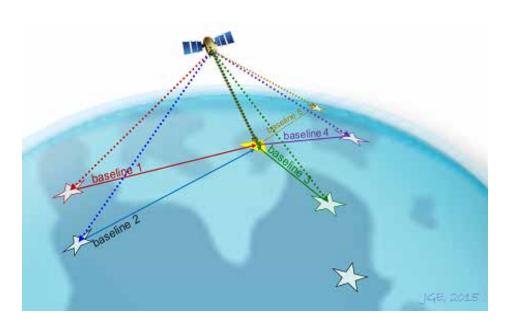
- Used when greater accuracy is required
- Excellent for large corridor surveys
- Rigorous Least Squares
 Adjustment

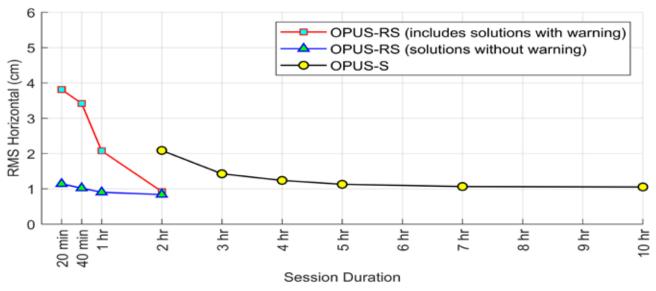


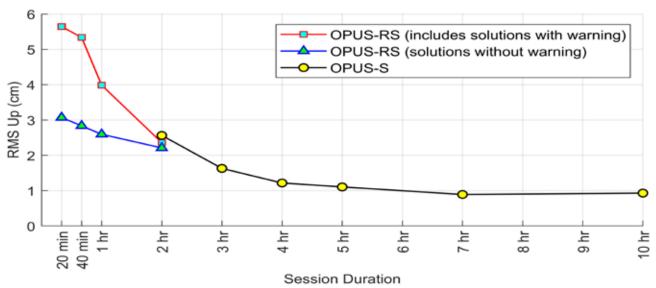
GNSS APPLICATIONS

§ OPUS

- Uses CORS Stations
- Can be Rapid-Static or Static
- Varying degrees of accuracy

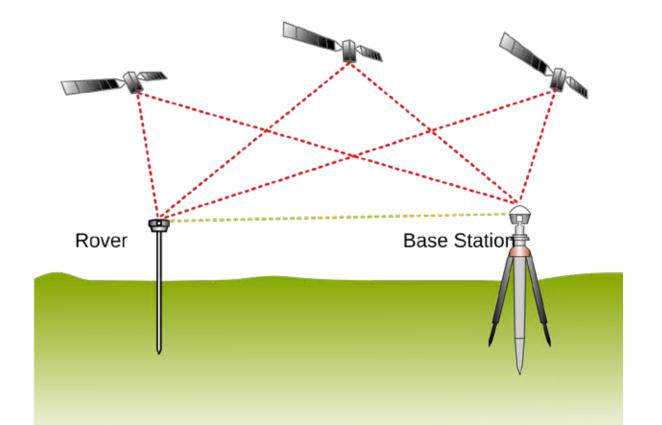






GNSS APPLICATIONS

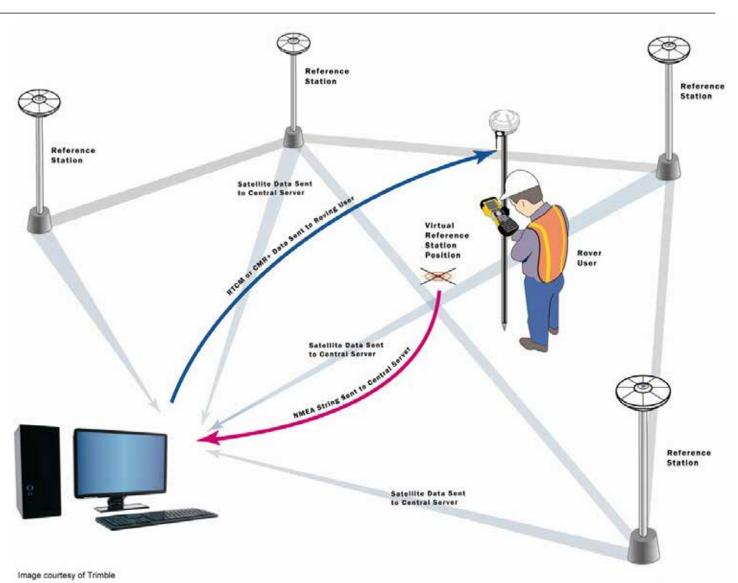
§ Local RTK utilizes real time corrections from on-site known base station to rover unit to establish positions.





GNSS APPLICATIONS

- § RTN and VRS (Real time Networks with Virtual Reference Stations
- § A commercial network of know reference stations collecting data
- § Computes a VRS that acts as a "local" base station



BATHYMETRIC SURVEYING

- § Bathymetric surves measure the depths and shape of underwater terrain, essentially creating a "map of the seafloor, rivers, or lakes".
- § Uses include
 - § Navigation safety
 - § Engineering & construction
 - § Environmental studies
 - § Flood modeling & hydrology
 - § Archaeology and exploration

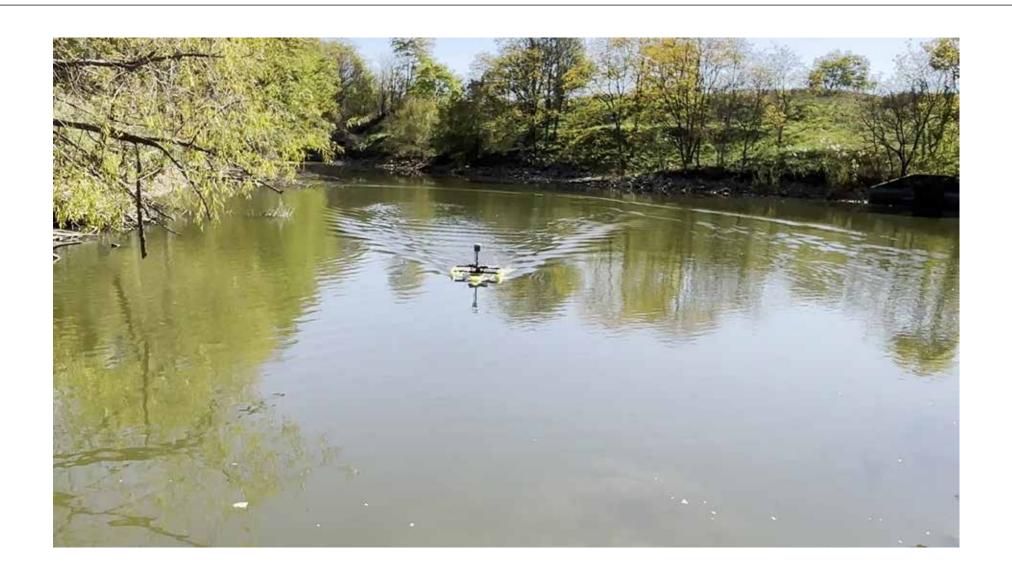




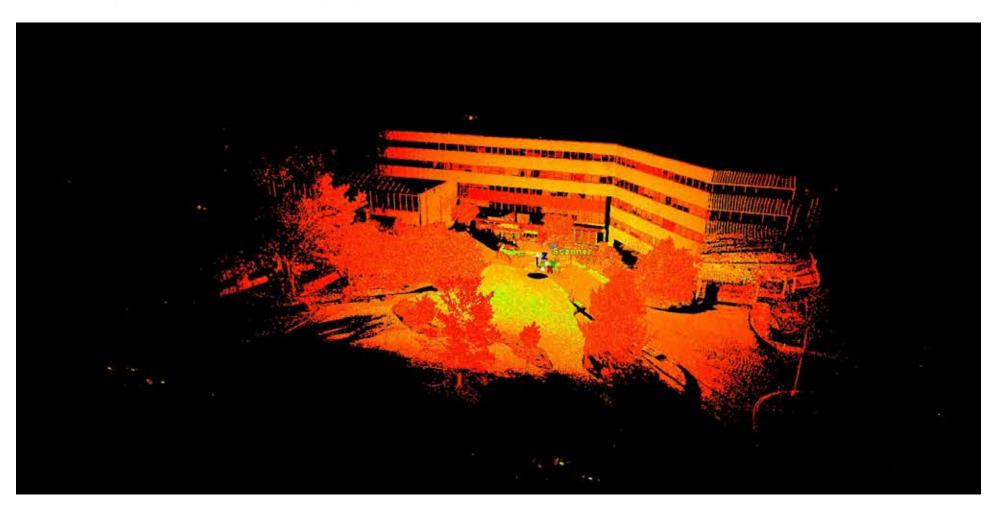
SPECIFICATIONS

- § Remote range: Up to 1 km (3280 ft)
- § Battery life 5 hours
- § HydroLite Sonar specifications;
 - § Sonar Depth- 0.5m-200m (1.64-656 ft)
 - § Depth Accuracy: 1cm/0.1% of depth





LIDaR – Light Image Detection and Ranging



TERRESTRIAL SCANNING

- § Most accurate
- § Provides the most detail
- § Easiest to use
- § Great for indoor and outdoor collection
- § Safe way to locate high traffic roadway





OUR EQUIPMENT

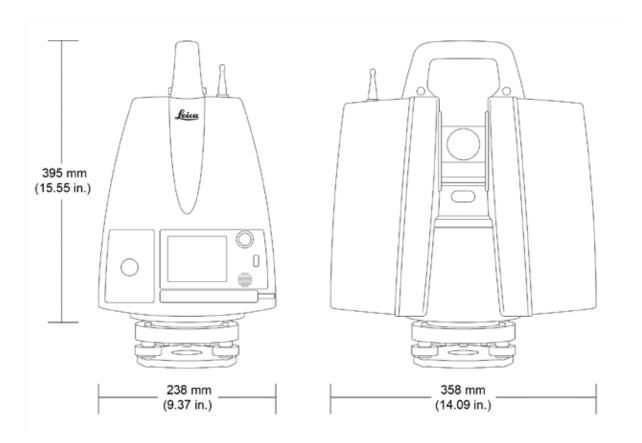
- § Leica P40 (Upgraded by Leica for Register 360)
- § Leica C10





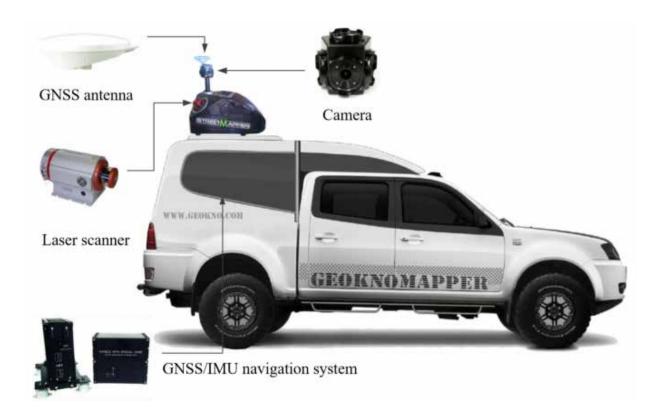
SPECIFICATIONS

- § Range 0.4 11470 m (1.31 37631 ft)
- § Speed Up to 1,000,000 pts/sec
- § Accuracies
 - § 0.4mm rms at 10m (0.00131 ft at 32.8 ft)
 - § 0.5mm rms at 50m (0.00164 ft at 164 ft)



MOBILE MAPPING

- § Can collect the most data in the shortest amount of time
- § Second most accurate
- § GPS real time locationing
- § Equipped for tunnels and GPS dead zones







Trimble MX90

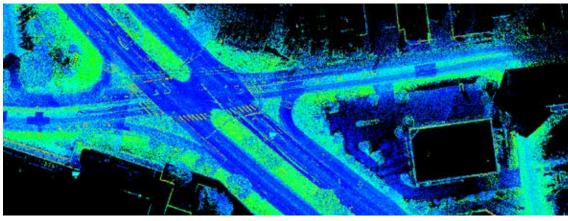
Mobile mapping system

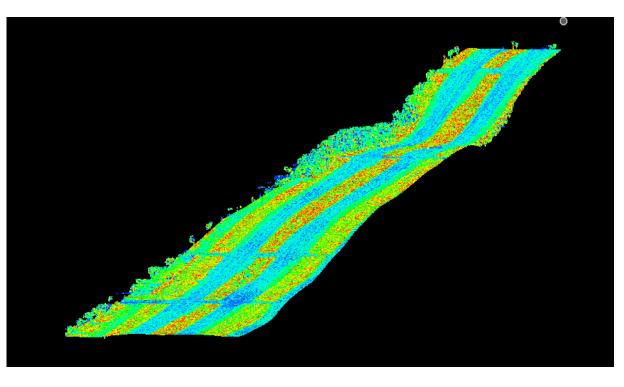
	MX90 SYSTEM			
	Scan speed	500 scans/sec		
	Number of laser scanners	2		
	Laser positions	Adjustable in 3 horizontal and 3 vertical positions		

Laser positions	Adjustable in 3 horizontal and 3 vertical positions							
MX90 LASER SCANNER								
Laser class	1, eye-safe							
EFFECTIVE MEASUREMENT RATE ¹	300 kHz	500 kHz	1000 kHz	1250 kHz	1500 kHz	1800 kHz		
Maximum range target reflectivity > 80% ²	475 m	370 m	235 m					
Maximum range target reflectivity > 10% ²	170 m	130 m	85 m					
Maximum number of targets per pulse	up to 15	up to 15	up to 9	up to 7	up to 5	up to 4		
Minimum range	1 m @ PRR ≥ 1 MHz, 1.2 m @ PRR < 1 MHz							
Accuracy³/precision⁴	5 mm/3 mm							
Field of view	ield of view 360° "full circle"							

CAMERAS								
SPHERICAL CAMERA	PHERICAL CAMERA							
Camera type	No	Mounting	FoV	Focal length				
Spherical camera, 72 MP (6 × 12 MP)	1	Fixed	90 % of full sphere	6.94 mm				
Capture modes	By distance or by time at 10 fps max							
PLANAR CAMERAS	PLANAR CAMERAS							
Camera type	No	Mounting	FoV	Focal length				
12 MP side facing camera	2	Adjustable (in horizontal and vertical positions)	H: 47.6° V: 35.9°	16.0 mm				
12 MP backward/ downward facing camera	1	Fixed	H: 82.9° V: 65.9°	8.0 mm				
Capture modes	By distance or by time at 9 fps max							





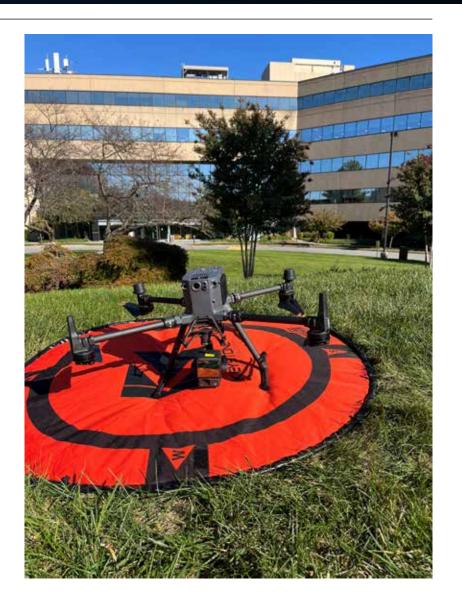




DRONE UAS SURVEYING

- § Minimal location disturbance
- § Second fastest data collection. Limited only by battery life.
- § Potential for future growth in accuracy and deployment





OUR EQUIPMENT

- § DJI Matric 350 RTK
- § Equipped with a L2 Lidar sensor payload

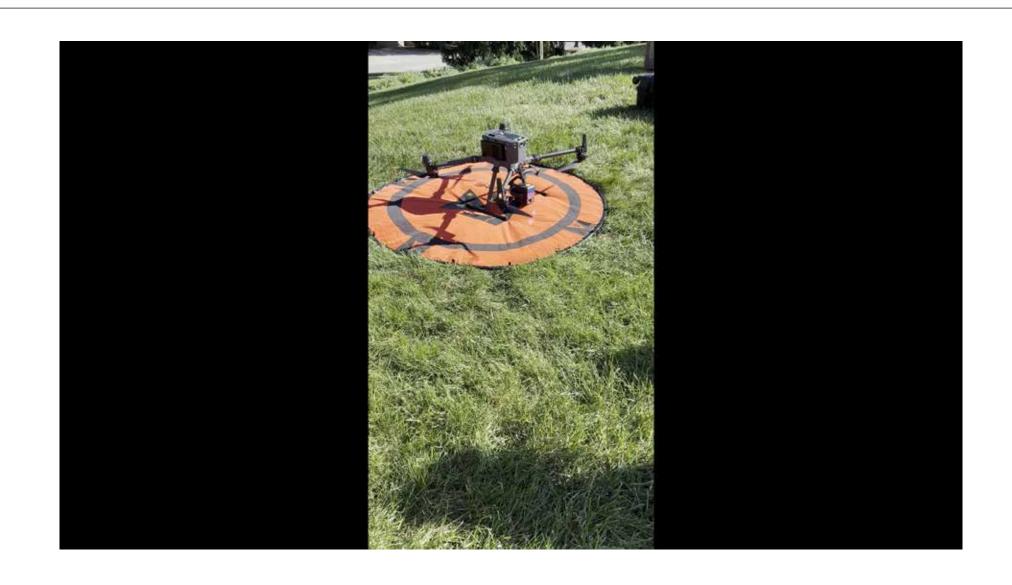




SPECIFICATIONS

- § Max flights time 55 minutes
- § Max speed 23m/s (51.45 mph)
- § Maximum tolerable wind speed 12m/s (23.3 knots)
- § Zenmuse L2
 - § 240,000 points per second
 - § Horizontal Accuracy 5cm @ 150 m (0.16 ft at 492 ft)
 - § Vertical Accuracy 4 cm @ 150 m (0.13 ft at 492 ft)







WHAT'S NEXT?





QUESTIONS?

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